REMES Tool-chain

A Set of Integrated Tools for Behavioral Modeling and Analysis of Embedded Systems

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ABSTRACT

In this paper, we present a tool-chain for the REMES language, which can be used for the construction and analysis of embedded system behavioral models. The tool-chain consists of the following tools: (i) a REMES editor for modeling behaviors of embedded components, (ii) a REMES simulator to test timing and resource behavior prior to formal analysis, and (iii) an automated transformation from REMES to Priced Timed Automata, needed for formal analysis.

Categories and Subject Descriptors
I.6.4 [Computing Methodologies]: Simulation and Modeling—Model Validation and Analysis; D.2.2 [Software Engineering]: Design Tool and Techniques

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Design, Performance, Verification

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behavioral modeling, component-based software engineering, embedded systems, formal analysis, simulation

1. INTRODUCTION

The top challenge in embedded systems (ES) design is the construction of systems with predictable behavior. In contrast to desktop systems, the embedded behaviors encompass not only functionality but also behaviors generated by constrained resources (CPU, energy, or memory), and/or timing constraints. Hence, to ensure the ES predictable behavior, one must employ analysis techniques, such as simulation, and/or formal analysis of the system’s model against various requirements.

As a first step towards achieving predictable systems, we have developed a hierarchical, timed behavioral language with graphical appeal, fit for a component-based ES design perspective. The crux of the language (see Figure 2), called the REsource Model for Embedded Systems (REMES) [6], is its ability to capture the resource-constrained and timing behavior of component-based ES, besides their functionality. REMES is inspired by CHARON [2], and, in comparison, treats resources as first-class modeling entities of discrete (e.g., memory) or continuous (e.g., energy) nature. REMES models can be transformed into the formal Timed Automata (TA) [3], or Priced Timed Automata (PTA) [1, 4], where one can compute the system’s worst-case/optimal resource-usage, as well as trade-offs between possibly conflicting resource-driven requirements. This is carried out by model-checking the resulted formal models with Uppaal\(^1\), or/and Uppaal Cora\(^2\) tools.

Figure 1: The REMES tool-chain workflow.

In this paper, we present a set of REMES tools that can be employed for the construction and analysis of ES behavioral models. Figure 1 illustrates the design flow implemented in our tool-chain. The designer uses: (i) a REMES editor (section 2) for building complex REMES models, (ii) a REMES simulator (section 3.1) that lets one test the timing and resource consumption of embedded

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\(^1\)The Uppaal tool is available at http://uppaal.com/.

\(^2\)The Uppaal Cora tool is available at http://www.cs.aau.dk/~behrmann/cora/.
connected by edges and conditional connectors. Each mode can have a number of associated constants, variables, and resources, displayed in separate compartments.

2. THE REMES EDITOR

The REMES editor is a graphical environment for behavioral modeling embedded components, in the semantics of the REMES modeling language. The diagram editor is based on the Graphical Modeling Framework (GMF) and the Eclipse Modeling Framework (EMF).

The REMES editor allows the user to easily create REMES artifacts such as atomic and composite modes, edges or conditional connectors. Submodes and conditional connectors can be nested inside composite modes. The user defines the control flow by creating edges between diagram elements. The action guards of the edges are defined by in-place editing in the diagram. Basic checks are performed to prevent the user from creating invalid models. The user can define typed variables, constants and resources in separate sections within the modes. The REMES diagram editor integrates with the Eclipse properties view, which displays and edits context sensitive information for the currently selected diagram element. Filters can be applied over the REMES diagram to outline a particular aspect of the REMES model – behavior, timing or resource usage. Figure 2 shows a screenshot of the REMES editor displaying a composite mode connected by edges and conditional connectors.

3. SIMULATION AND FORMAL ANALYSIS OF REMES MODELS

3.1 The REMES simulator

Simulating and testing the system behaviors as they are being designed can provide valuable input to the designer. Once completed, REMES models can be model-checked in tools like Uppaal. We use model-to-text transformations (M2T) to transform behaviors into source code that simulates the modeled system. The transformation is performed over intermediate models created from REMES diagrams that retain the internal behavior structure. The user can then run the simulator which updates mode variables and resources in each simulation round, based on passed time. The system designer can visualize the mode transitions, the clock- and variable changes in the simulator output.

3.2 Transforming REMES into PTA

The transformation of REMES models into PTA is implemented by the model-to-model (M2M) transformation language ATL (Atlas Transformation Language). The basic transformation rules are as follows: (i) a REMES diagram (see Figure 2) is transformed to a network of PTA, (ii) a composite mode is transformed to a single PTA, (iii) submodes, init-, entry-, and exit points, and conditional connectors are removed in PTA, (iv) invariants and guards referring to resources are translated to a PTA cost variable, as a weighted sum of REMES resources (declared in $\mathbf{\Phi}$), and (v) additional start location is added to each PTA to allow initialization.

The transformation rules applied to REMES diagrams result in UppaalLite models representing the same behavior. A graphical editor for UppaalLite models is provided, as a tool to visually inspect transformation results. Model files for both Uppaal (TA) and Uppaal CORA (PTA) can be exported for formal verification and analysis.

When using the REMES tool-chain within integrated development environments, e.g., Prime, the transformation uses component triggering information from architectural models, to insert appropriate synchronization channels into the resulting PTA.

4. REFERENCES


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Figure 2: A screenshot of the REMES editor. A composite mode consists of several submodes (atomic modes) connected by edges and conditional connectors. The modes are entered via their init- or entry-points, and exited through their exit-points. Each mode can have a number of associated constants, variables, and resources, displayed in separate compartments.

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$\Phi$The REMES tool-chain is available at http://www.fer.hr/dices/remes-ide.

$\Phi$The Prime toolset is available at http://www.idt.mdh.se/prime/.