



Towards model-based Generation and Optimization of AUTOSAR Runnable-to-Task Mapping

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Agenda

Motivation

Deployment of runnables in the context of AUTOSAR

Use cases

AUTOSAR Configuration Generation Meta-model

Initial ECU Configuration Generation

Case study

ECU Configuration Optimization

Outlook



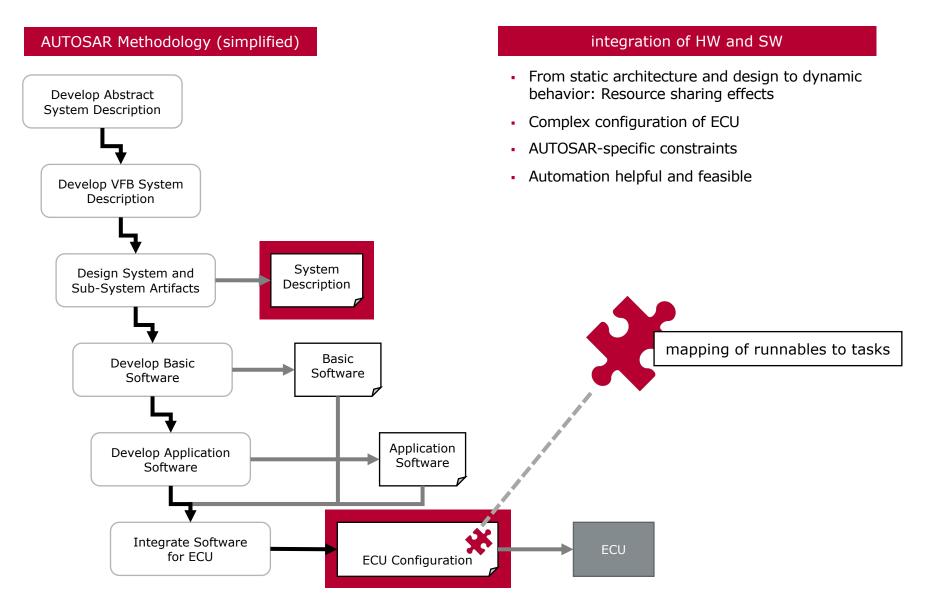
Motivation

	MA.	Wst.	lst-Std./Soll-Std	Qualifikation	6.10	7.10	8.10	9.10	10.10	11.10	12.10	13.10	14.10	15.10	16.10	17.10
8. Past	2.9	38.5	47.0	Examiniert									N	N	N	N
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	0.0	38.5	124.0 115.6	Examiniert	F	F	 Pflegekraft K. Wolff hat zwischen diesem Nachtschichtblock (4.10 - 7.10) und dem Anfang des näc Nachtschichtblockes (20.10) nur 12 Tag(e) Abstand, also 4 Tag(e) zu wenig. 									
0.000	1.9	38.5	118.2	Schüler/in	F	F	an									
rühschicht					E4/5-S1/1	E5/5-S1/1	E									
pätschicht					E6/5-S1/1	E6/5-S1/1	E5/5-S1/1	E5/5-S0/0	E6/5-S0/0	E5/5-S1/1	E5/5-S1/1	E5/5-S1/1	E6/5-S1/1	E5/5-S1/1	E5/5-S0/0	E6/5-S
chtschicht					E6/5-S1/1	E6/5-S1/1	E5/5-S1/1	E5/5-S0/0	E6/5-S0/0	E5/5-S1/1	E5/5-S1/1	E5/5-S1/1	E6/5-S1/1	E5/5-S1/1	E5/5-S0/0	E6/6-S

Universität Würzburg: Wissensbasierte Dienstplanung [http://www.is.informatik.uni-wuerzburg.de/research-tools-download/weitere-anwendungen/dienstplanung/]



Deployment in the context of AUTOSAR



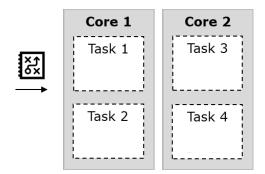
use case 1A



Mapping Runnable Entities to OS Tasks

create an init	ial configurat	ion	optimize an existing configuration							
•	and may contain unnables to the		use case	A configuration exists: Optimize the existing configuration by finding a new mapping						
×××	Core 1 Task 1 R6 R8 Task 2 R1 R4	Core 2 Task 3 R2 R3 R5 R7 R9	Core 1 Task 1 R6 R7 Task 2 R1	Core 2 Task 3 R2 R3 Task 4 R5 R4	\$\$	Core 1 Task 1 (7) (R3) Task 2 (R1) (R5)	Core 2 Task 3 R2 Task 4 R6 R4			

use case 1B Tasks do not exist: Create suitable tasks*, map the runnables to them





constraint programming

evolu

evolutionary algorithm

 \ast Creating tasks is challenging (see Hoettger et al. (2015)) and work in progress.



AUTOSAR configuration generation meta-model

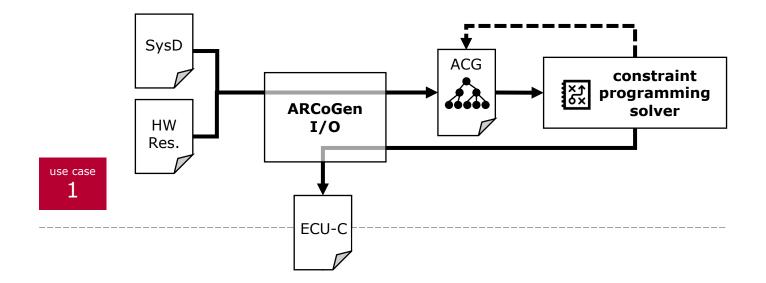
TimeSphere

level: NodeLevel safetyLevel: SafetyLevel validMappingTarget: boolean

...



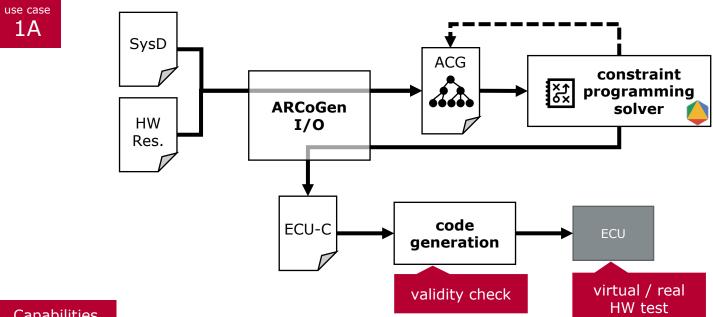
Using the meta model



ACG = model instance
ARCoGen = AUTOSAR Configuration Generator
SysD = System Description (AUTOSAR)
HW Res. = Hardware Resource Template (AUTOSAR)
ECU-C = ECU configuration (AUTOSAR)



Approach



- Capabilities
- Consider AUTOSAR-specific constraints
- Optimization goals: balanced core utilization, communication cost (in progress)
- Task synthesis (in progress)

Challenges

- Basic software
- Utilization caused by non-periodic runnables

Initial ECU configuration generation



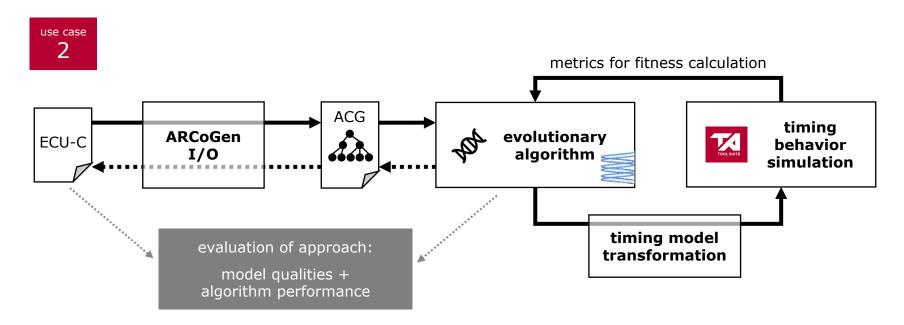
Case study

- Goal: evaluate feasibility of approach
- Input:
 - ▶ Test model with 18 SWCs, 50 runnables, 26 tasks overall
 - System description
 - HW resource template (tri-core ECU)
 - Execution times from measurement trace
- Method:
 - Use existing test model as reference
 - Generate a new mapping
 - Evaluate result using existing AUTOSAR toolchain
- Result:
 - Generated mapping is valid (DaVinci Configurator analysis + code generation)
 - ▶ Test of functionality on virtual target successful
 - Simulation to gain utilization data
 - Utilization is more balanced (see limitations)
- Limitations:
 - Utilization only considered for periodic runnables
 - Basic software is not considered
 - Security not considered in the test model

model	U of C1	U of C2	U of C3
reference	23,14%	9,97%	4,87%
generated (incl. non-periodic)	13,67%	10,26%	12,80%
generated (excl. non-periodic)	10,62%	8,13%	9,74%
delta (generated incl./excl.)	3,05%	2,13%	3,06%



Approach

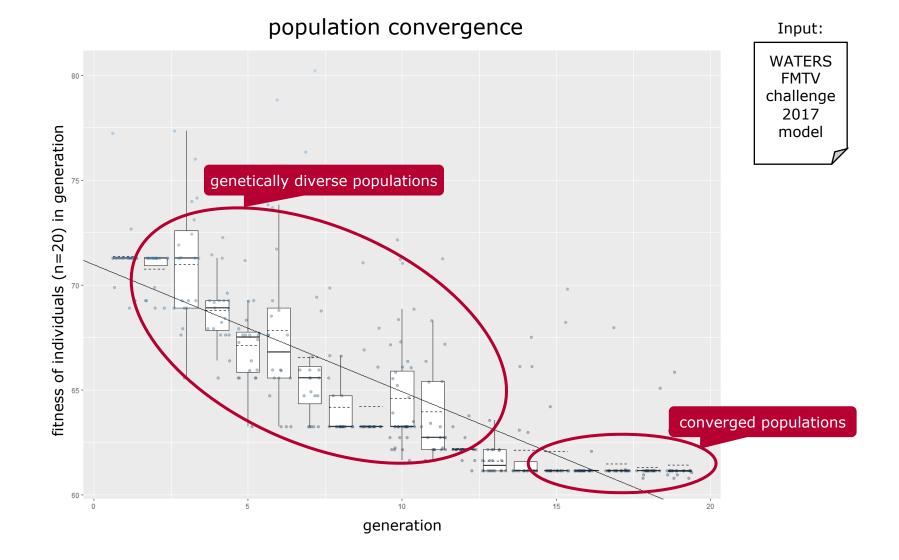


challenges

- Locality of the problem representation
- Cost of fitness calculation
- Constraint-aware evolutionary operators (search vs. solution space)
- ▶ Evaluation of results (validity, user) and algorithm performance (duration, convergence, ...)
- ▶ Use case specific algorithm design and parameters



Algorithm performance evaluation





Outlook

Initial configuration generation:

- Communication cost as optimization goal
- ► Gather user feedback

Configuration optimization:

- ► Find operators that respect AUTOSAR constraints
- Identify common algorithm designs and parameters for problem classes (what classes are there?) using the experiment toolchain

Challenges in the wild:

- Data quality: Garbage in, garbage out
- Size of input models might be prohibitive



Your questions are welcome!

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